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An exact formula for electromagnetic momentum in terms of the charge density and the Coulomb gauge vector potential

Hanno Essén

Department of Mechanics Royal Institute of Technology SE-100 44 Stockholm, Sweden

E-mail: hanno@mech.kth.se

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Abstract

The electromagnetic momentum $p = 1/(4\pi c) \int E \times B dV$ is sometimes approximated by $p_0 = (1/c) \int \rho A dV$, where ρ is the charge density and A is the Coulomb gauge vector potential. Here, we show that p_0 is the first term in an exact two-term expression $p = p_0 + p_1$ where the second term refers to radiation. When the charge density is zero, $p = p_1$ is the momentum of fields propagating in vacuum. In the presence of charged particles, however, p_0 normally dominates. We argue that p_0 is the natural formula for the electromagnetic momentum when radiation can be neglected. It is shown that this term may in fact be much larger than the purely mechanical contribution from mass times velocity.

Keywords: electromagnetic momentum, Coulomb gauge, Darwin Lagrangian, canonical momentum

1. Introduction

Electromagnetic momentum is the contribution to the momentum of a system from electromagnetic fields which must be added to the usual momentum, due to mass times velocity, to the get the total momentum that is conserved for a closed isolated system. Fundamental considerations involving the energy momentum tensor of the electromagnetic field give the electromagnetic momentum density (in Gaussian units) as

$$\boldsymbol{G} = \frac{1}{4\pi c} \boldsymbol{E} \times \boldsymbol{B}.$$
 (1)

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The momentum is then the volume integral of this density

$$\boldsymbol{p} = \frac{1}{4\pi c} \int \boldsymbol{E} \times \boldsymbol{B} \, \mathrm{d} \boldsymbol{V}. \tag{2}$$

The momentum density vector field is proportional to the Poynting vector $S = c^2 G$, giving the energy flux density in the field.

Here, we will analyze this expression using concepts of classical electrodynamics. We will find that this this expression, in a natural way, can be divided into two parts $p = p_0 + p_1$ of very different physical significance. One part, here denoted p_0 , which often is quite large, is due the presence of moving charged particles and applies to electric currents in conductors and electric oscillations in plasmas—see equation (3), below. The remaining part, p_1 —normally much smaller—is due to electromagnetic waves propagating in vacuum. It is important to be aware of the existence of these two parts, and the distinction between them.

An approximate result, which goes all the way back to Maxwell, is that

$$\boldsymbol{p} \approx \boldsymbol{p}_0 = \frac{1}{c} \int \rho \boldsymbol{A} \, \mathrm{d} \boldsymbol{V},\tag{3}$$

where ρ is the charge density and A is the Coulomb gauge vector potential. This formula gives the otherwise somewhat abstract vector potential a concrete meaning, and is therefore of great interest. The circumstances under which this approximation is valid are often vaguely described as the quasi-static approximation, 'when higher order terms in v/c can be neglected' or 'when the effects of radiation and retardation can be ignored'. Discussions of this and other approximations are by Furry [1], Carpenter [2], Gsponer [3], Griffiths [4], McDonald [5], Lorrain [6], and Hu [7]. Interpretation of the vector potential as potential momentum per charge have been advocated by Calkin [8, 9], Konopinski [10, 11], Gingras [12], and Semon and Taylor [13], among others. These concepts have also been much discussed in connection with hidden momentum ideas (see e.g. Aguirregabiria *et al* [14, 15], Hnizdo [16], Johnson *et al* [17], Babson *et al* [18], Boyer [19], Redfern [20]).

After deriving $p = p_0 + p_1$, and discussing the nature of the two terms, we focus on p_0 , and motivate it as the natural momentum expression arising from the Darwin Lagrangian [21]. We also estimate the electromagnetic contribution to the total momentum as compared to the kinetic contribution MV for a system of collectively moving charged particles. For macroscopic numbers of particles, the electromagnetic contribution in fact dominates—a fact rarely pointed out in the literature. From all this, we conclude that (3) may be regarded as the most natural and useful expression for electromagnetic momentum, as long as radiation can be neglected.

2. The two parts of the electromagnetic momentum density

Maxwell's homogeneous equations are identically satisfied if one assumes that the fields are given by

$$E = -\nabla \phi - \frac{1}{c} \frac{\partial A}{\partial t}, \text{ and } B = \nabla \times A,$$
 (4)

in terms of scalar ϕ and vector **A** potentials. When this is inserted into Maxwell's inhomogeneous equations, one finds (see Jackson [22], sections 6.2 and 6.3)

$$\nabla^2 \phi + \frac{1}{c} \frac{\partial}{\partial t} (\nabla \cdot \mathbf{A}) = -4\pi \varrho, \qquad (5)$$

$$\Box \mathbf{A} - \nabla \left(\frac{1}{c}\frac{\partial \phi}{\partial t} + \nabla \cdot \mathbf{A}\right) = -\frac{4\pi}{c}\mathbf{j}.$$
(6)

When the bracket in equation (6) is put to zero, the Lorenz gauge, both these equations become inhomogeneous wave equations. If one instead chooses the Coulomb (or transverse, or radiation) gauge by $putting^1$

$$\nabla \cdot \boldsymbol{A} = \boldsymbol{0},\tag{7}$$

one finds that

$$\nabla^2 \phi = -4\pi \varrho,\tag{8}$$

$$\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}\right) \mathbf{A} = -\frac{4\pi}{c} \mathbf{j}_t.$$
(9)

Here,

$$\mathbf{j}_t = \mathbf{j} - \frac{1}{4\pi} \nabla \frac{\partial \phi}{\partial t} \tag{10}$$

is the transverse current density which thus acts as source of the Coulomb gauge vector potential. This current density is divergence free, $\nabla \cdot \mathbf{j}_t = 0$, as is seen using the equation of continuity.

To get the momentum density, we now insert equations (4) in the definition (1), to get

$$\boldsymbol{G} = \boldsymbol{G}_0 + \boldsymbol{G}_1, \tag{11}$$

where

$$\boldsymbol{G}_0 = -\frac{1}{4\pi c} \nabla \phi \times (\nabla \times \boldsymbol{A}), \tag{12}$$

$$\boldsymbol{G}_{1} = -\frac{1}{4\pi c^{2}} \frac{\partial \boldsymbol{A}}{\partial t} \times (\nabla \times \boldsymbol{A}).$$
(13)

It is now elementary to show that

$$\boldsymbol{p}_0 = \int \boldsymbol{G}_0 \, \mathrm{d}V = \frac{1}{c} \int \varrho \boldsymbol{A} \, \mathrm{d}V, \tag{14}$$

assuming (7), (8), and that certain surface integrals go to zero at infinity. The derivation is given in an appendix. We see that the momentum is given entirely in terms of the charge density and the Coulomb gauge vector potential and its derivatives.

The exact electromagnetic momentum is $p = p_0 + p_1$, where

$$\boldsymbol{p}_1 = \int \boldsymbol{G}_1 \, \mathrm{d}V = \frac{-1}{4\pi c^2} \int \frac{\partial \boldsymbol{A}}{\partial t} \times (\nabla \times \boldsymbol{A}) \, \mathrm{d}V = \frac{1}{4\pi c^2} \int \boldsymbol{B} \times \frac{\partial \boldsymbol{A}}{\partial t} \, \mathrm{d}V. \tag{15}$$

This part is of higher order in v/c than p_0 , as shown below, and is related to radiation.

2.1. Orders of magnitude and dimensional analysis

In the Gaussian unit system, A has the same dimension as ϕ , namely charge Q divided by length L, but the vector potential is multiplied by v/c, where v is the speed of the charged

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¹ This gauge condition, together with suitable boundary conditions, implies unique solutions.

particles producing the current—see (18) below. Also, Q^2/L has dimension energy, and therefore this quantity divided by c^2 has dimension mass M.

Using this, the dimension of p_0 can be written

$$[\mathbf{p}_0] = \frac{1}{c^2} \frac{Q^2}{L} v = M v.$$
(16)

Doing the same analysis for p_1 (putting $[c\partial t] = L$ and $[\nabla] = 1/L$) gives

$$[\mathbf{p}_1] = \frac{1}{c^2} \frac{Q^2}{L} \frac{v}{c} v = \frac{v}{c} M v.$$
(17)

We see that both quantities have dimension mass times velocity, as they should, but p_1 is multiplied by an extra dimensionless factor v/c.

3. The message of the Darwin Lagrangian

The Darwin Lagrangian [21] describes most electromagnetic phenomena quite well, with the exception of radiation, which is neglected. The theory behind this Lagrangian is presented in well known textbooks such as Landau and Lifshitz [23, section 65] and Jackson [22, section 12.6]. More extensive discussions can be found in Page and Adams [24, section 96], Podolsky and Kunz [25, section 27], or Schwinger *et al* [26, equation (33.23)]. Basic articles of interest are Breitenberger [27], Kennedy [28], Essén [29, 30]. Various applications of the Darwin Lagrangian illustrating its usefulness can be found in Stettner [31], Boyer [32, 33], Essén [34–37], and Essén and Fiolhais [38].

The vector potential is not always mentioned in connection with the Darwin Lagrangian, but basically the central idea is to approximate the Liénard–Wiechert potentials. Landau and Lifshitz [23, section 65], make a gauge transformation to the Coulomb gauge after truncating series expansions of these. Jackson [22, section 12.6], argues that it is sufficient to simply solve the vector Poisson equation obtained by neglecting the time derivatives in equation (9). For a point charge e with velocity v at the origin, the resulting divergence free (Coulomb gauge) vector potential at r is given by

$$A(\mathbf{r}, \mathbf{v}) = \frac{e}{2c} \frac{\mathbf{v} + (\mathbf{v} \cdot \hat{\mathbf{e}})\hat{\mathbf{e}}}{r}.$$
(18)

Here \hat{e} is the unit vector r/r.

The Darwin Lagrangian can be written

$$L_{\rm D} = \sum_{a=1}^{N} \left[L_m(\mathbf{v}_a) - \frac{e_a}{2} \phi_a(\mathbf{r}_a) + \frac{e_a}{2c} \mathbf{v}_a \cdot \mathbf{A}_a(\mathbf{r}_a) \right],\tag{19}$$

where

$$\phi_a(\mathbf{r}) = \sum_{b(\neq a)}^N \frac{e_b}{|\mathbf{r} - \mathbf{r}_b|},\tag{20}$$

and

$$\boldsymbol{A}_{a}(\boldsymbol{r}) = \sum_{b(\neq a)}^{N} \frac{\boldsymbol{e}_{b} \left[\boldsymbol{v}_{b} + (\boldsymbol{v}_{b} \cdot \hat{\boldsymbol{e}}_{b})\hat{\boldsymbol{e}}_{b}\right]}{|\boldsymbol{r} - \boldsymbol{r}_{b}|}.$$
(21)

Here, $\hat{\boldsymbol{e}}_b = (\boldsymbol{r} - \boldsymbol{r}_b)/|\boldsymbol{r} - \boldsymbol{r}_b|$, while $L_m(\boldsymbol{v})$ is the Lagrangian of a free particle. Depending on the application this may or may not be relativistic. Normally the non-relativistic version $L_m(\boldsymbol{v}) = m\boldsymbol{v}^2/2$ will do.

For a Lagrangian L the canonical momentum of particle a is defined as

$$\boldsymbol{p}_a = \frac{\partial L}{\partial \dot{\boldsymbol{r}}_a} = \frac{\partial L}{\partial \boldsymbol{v}_a}.$$
(22)

and this applied to the Lagrangian (19) gives $(\hat{e}_{ba} = (r_a - r_b)/|r_a - r_b|)$

$$\boldsymbol{p}_{a} = \boldsymbol{\pi}_{a} + \sum_{b(\neq a)} \frac{e_{a}e_{b}}{r_{ba}} \frac{[\boldsymbol{v}_{b} + \hat{\boldsymbol{e}}_{ba}(\boldsymbol{v}_{b} \cdot \hat{\boldsymbol{e}}_{ba})]}{2c^{2}},$$
(23)

where π_a is the mechanical momentum, often simply $m_a v_a$, but more generally $\partial L_m / \partial v_a$ which may include relativistic effects. This equation can be found in Schwinger *et al* [26] as equation (33.24). We can write this as

$$\boldsymbol{p}_a = \boldsymbol{\pi}_a + \frac{\boldsymbol{e}_a}{c} \boldsymbol{A}_a(\boldsymbol{r}_a), \tag{24}$$

using equation (21).

If the charge density of point particles,

$$\varrho(\mathbf{r}) = \sum_{a} e_a \delta(\mathbf{r} - \mathbf{r}_a), \tag{25}$$

is inserted into equation (14) we find that

$$\boldsymbol{p}_0 = \sum_a \frac{e_a}{c} \boldsymbol{A}(\boldsymbol{r}_a). \tag{26}$$

This is evidently the sum of the electromagnetic parts of the canonical momenta of equation (24).

Hence the total electromagnetic momentum according to the Darwin Lagrangian is exactly given by the formula (14) when ρ is the charge density of point particles. We conclude that the expression (14) and electromagnetic momentum as obtained from the Darwin Lagrangian agree. When one can neglect radiation, this should thus be considered as the most natural formula for the electromagnetic momentum.

3.1. The total momentum of collectively moving charges

Let us estimate the total momentum of *N* particles of mass *m* and charge *e* moving collectively with velocity *V*. If we assume that the typical distance between the particles is *R*, we can get a rough estimate for the total momentum $P = \sum_{a=1}^{N} p_a$ using (23). We find

$$\boldsymbol{P} = N\boldsymbol{m}\boldsymbol{V} + N^2 \frac{e^2}{c^2 R} \boldsymbol{V} = N\boldsymbol{m} \left(1 + \frac{e^2}{mc^2} \frac{N}{R} \right) \boldsymbol{V}.$$
(27)

If we put M = Nm for the total (rest) mass, and note that $r_e = \frac{e^2}{mc^2}$ is the classical electron radius, we find

$$\boldsymbol{P} = M \left(1 + \frac{Nr_{\rm e}}{R} \right) \boldsymbol{V} = M(1+\nu)\boldsymbol{V}.$$
⁽²⁸⁾

The dimensionless number $\nu = \frac{N_{r_e}}{R}$, which might be called the Darwin number, is thus an indicator of whether the effective inertial mass of the moving charges is dominated by rest

mass M ($\nu \ll 1$) or if it is dominated by the effective mass of the resulting magnetic energy ($\nu \gg 1$).

Darwin himself [39] studied the inertia of electrons in metals, and found that for ordinary conduction electrons the inductive inertia is many orders of magnitude larger than the sum of the rest masses of the electrons. Many textbooks derive the—so called—plasma frequency,

$$\omega_{\rm p} = \sqrt{\frac{ne^2}{m}} \tag{29}$$

where *n* is the number density of electrons. In that derivation, it is assumed that the inertia is due to the electron rest mass *m*. When the Darwin number is large, this is clearly not correct. Essén [34], in a calculation based on the Darwin Lagrangian shows that the mass in the denominator should be replaced by $m(1 + \nu)$ to get better estimates of the frequency of collective oscillations in plasmas.

4. Conclusions

The Coulomb gauge requirement, $\nabla \cdot A = 0$, is crucial in the derivations above. The Darwin Lagrangian is, however, rarely written explicitly in the form (19) with the vector potential, even if the expression (18) is obtained as an intermediate step in Jackson [22], equation (12.80), as well as Landau and Lifshitz [23], equation (65.6). The choice of the Coulomb gauge has the result that relativistic effects, including *retardation*, are taken into account to order $(v/c)^2$ by the Darwin Lagrangian. This is somewhat obscured by Jackson's derivation, but is clear from Darwin's [21] original derivation, as well as in Landau's and Lifshitz'. A Coulomb gauge vector potential correct to all orders in v/c has been derived by Hnizdo [40], and its implications for the Darwin formalism have been discussed by Essén [41]. More information on the significance of the Coulomb gauge can be found in Jackson [42]. It is advantageous to use when there is a natural rest frame with respect to which velocities are small, so that relativistic invariance is of less importance.

One reason that the expression (14) for the electromagnetic momentum is rarely advocated is that the vector potential is not seen as unique, due to gauge freedom (see Berche *et al* [43]). However, as often pointed out the gauge freedom does not pose any real difficulty. The physically interesting vector potential should go to zero with distance from its source and should be singular at a point particle source, just as the Coulomb potential. One should also note that the Darwin vector potential (21) has no gauge freedom. It is given by a superposition of terms (18), one for each moving charged point particle, and this vector potential is the natural one to use.

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Appendix

The derivation of (14) given below is sketched in e.g. Trammell [44] and Kittel [45], see appendix G—but these derivations are a bit brief and hard to follow. A more careful proof is given below.

Using the three-dimensional antisymmetric unit tensor e_{ijk} , one can write the *i*th component of a vector product $(\boldsymbol{a} \times \boldsymbol{b})_i = e_{ijk}a_jb_k$ where summation over the repeated indices from 1 to 3 is implied. Using the Kronecker δ_{ij} , a scalar product can similarly be written $\boldsymbol{a} \cdot \boldsymbol{b} = \delta_{ij}a_ib_j = a_ib_i$. The *i*th component of $\boldsymbol{u} = \nabla \phi \times (\nabla \times \boldsymbol{A})$ can be written

$$u_i = e_{ijk} \partial_j \phi \ e_{klm} \partial_l A_m. \tag{30}$$

Here $\partial_i = \partial/\partial x_i$. From this, we get

$$u_i = e_{ijk} e_{klm} \partial_j \phi \ \partial_l A_m = e_{ijk} e_{lmk} \partial_j \phi \ \partial_l A_m. \tag{31}$$

Using the identity (see e.g. Landau and Lifshitz [23, page 18])

$$e_{ijk}e_{lmk} = \delta_{il}\delta_{jm} - \delta_{im}\delta_{jl},\tag{32}$$

we find

$$u_{i} = (\delta_{il}\delta_{jm} - \delta_{im}\delta_{jl})\partial_{j}\phi \ \partial_{l}A_{m} = \delta_{il}\partial_{j}\phi \ \partial_{l}A_{j} - \delta_{im}\partial_{j}\phi \ \partial_{j}A_{m},$$
(33)

so

$$u_i = \partial_j \phi \; \partial_i A_j - \partial_j \phi \; \partial_j A_i. \tag{34}$$

When integrating this over the volume containing the system we would like to have terms that are divergences, so that we can use Gauss' theorem to turn them into surface integrals. These should then go to zero as the distance to the surface goes to infinity. To achieve this we use that

$$u_i = \partial_j (\phi \ \partial_i A_j) - \phi \ \partial_j \partial_i A_j - \partial_j (\partial_j \phi \ A_i) + (\partial_j \partial_j \phi) A_i.$$
(35)

This can be written

$$u_i = \nabla \cdot (\phi \ \partial_i \mathbf{A}) - \phi \ \partial_i \nabla \cdot \mathbf{A} - \nabla \cdot (A_i \nabla \phi) + (\nabla^2 \phi) A_i. \tag{36}$$

Using $\nabla \cdot A = 0$ and $\nabla^2 \phi = -4\pi \rho$, this becomes

$$u_i = \nabla \cdot (\phi \ \partial_i A - A_i \nabla \phi) - 4\pi \rho A_i. \tag{37}$$

Integrating this over a volume V contained in a closed surface S, Gauss' theorem gives

$$\int_{V} u_{i} \mathrm{d}V = \int_{S} \left(\phi \ \partial_{i} \mathbf{A} - A_{i} \nabla \phi \right) \cdot \mathrm{d}\mathbf{S} - \int_{V} 4\pi \varrho A_{i} \mathrm{d}V.$$
(38)

For particles and currents in a limited region of space, one should have $\phi \sim 1/r$ and $A_i \sim 1/r^2$ for large distance *r* from the region. Since these quantities are differentiated in the two terms in the surface integral, these should behave as $\sim 1/r^4$ with distance *r*. So, making the volume big enough, the surface integrals become negligible, and we have

$$\int \boldsymbol{u} \mathrm{d}V = \int \nabla \phi \times (\nabla \times \boldsymbol{A}) \mathrm{d}V = -\int 4\pi \rho \boldsymbol{A} \mathrm{d}V$$
(39)

when integrating over all space².

ORCID iDs

Hanno Essén ⁽ⁱ⁾ https://orcid.org/0000-0003-0130-9643

 $^{^{2}}$ Having derived this result Trammell [44] applies it to the infinite solenoid. One should note, however, that results that are derived assuming that surface integrals are zero at infinity do not necessarily apply to infinite solenoids.

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